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Last Time: Determinants
             Prop: Every metrix M can be expressed as
                                                 M = E. E. - ... E, RREF (M)
 Recall: det is multiplizative.
                           i.e. det (AB) = det (A) det (B).
                         Point: O Computing RREF (M) can also compute det (M).
                                                  3 Let (M) = Let (En) Let (En.) ... Let (E) · det (RREF(M))
                                                                             Change of Basis ("with respect to"
Recall: Given basis B= $6,,62, ..., by of V.S. V, every vector of V has a sepresentation write B.
            VEV can be expressed uniquely as v = \sum_{j=1}^{n} C_{i} b_{j}.
                 The corresponding representation is [v]_B = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \in \mathbb{R}^n.
 NB: RepB(v) is the textbook's notation for [v]13
  Ex: In \mathbb{R}^3 \mathbb{R
                 \begin{bmatrix} V \end{bmatrix}_{\mathcal{E}_3} = \begin{pmatrix} 2 \\ -3 \\ 5 \end{pmatrix} \longrightarrow \text{ whit } \text{w.r.t. } \mathbb{B}?
         C_{1}\begin{pmatrix} 1\\0\\0 \end{pmatrix} + C_{2}\begin{pmatrix} 1\\1\\0 \end{pmatrix} + C_{3}\begin{pmatrix} 1\\1\\1 \end{pmatrix} = \begin{pmatrix} 2\\-3\\5 \end{pmatrix} \longrightarrow \begin{cases} C_{1} + C_{2} + C_{3} = 2\\ C_{2} + C_{3} = -3\\ C_{3} = 5 \end{cases}
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$$\begin{bmatrix} 1 & 1 & | & 2 \\ 0 & 1 & | & | & -3 \\ 0 & 0 & | & -8 \\ 0 & 0 & | & -8 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & | & 5 \\ 0 & 1 & | & -8 \\ 0 & 0 & | & | & 5 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & | & 5 \\ 0 & 1 & | & -8 \\ 0 & 0 & | & | & 5 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & | & 5 \\ 0 & 1 & | & -8 \\ 0 & 0 & | & | & 5 \end{bmatrix}$$

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(siven two bases B, B' of vector spaces V and V' respectively, and given function $f:B \to B'$ there is a corresponding linear map $F:V \to V'$ with $F(\sum_{i=1}^{n} c_i b_i) = \sum_{i=1}^{n} c_i f(b_i)$.

Defn: A change of basis metrix is the untrix of a linear up L:V->V such that L is induced by a bijection L:B->B' for the bases B,B' of V

Ex: Let $B = \{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \}$ and $B = E_3 = \{e_1, e_2, e_3\}$ The change of besis metrix for these bases is... $\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$

: the change of basis mitor B to B' is

Rep_B, B'(id) = [1-10].

Point: Representation untix Reps, B' (il) when explied to [v]B outputs [v]B'. J.E. RepB,B'[V]B = [V]B'. NB. KB'B, (:Y) = [[p']B, [p']B, | ... | [pn]B,] Ex: Let B = {(2), (1)} and B'= {(1), (1)} We compte RepB,B' (id) as follows: [B' |B] = [Islay [-1 1 2 1] m [1 -1 | -2 -1] m_{3} $\begin{bmatrix} 1 & 0 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & 1 & \frac{3}{2} & \frac{1}{2} \end{bmatrix}$: RepB (id) = [-1/2 - 1/2] OTOH Reps, B (id): B B'] -> [In | RepB', B(id)] $\begin{bmatrix} 2 & | & -1 & | \\ 1 & 0 & | & 1 \end{bmatrix}$ $\rightarrow \begin{bmatrix} 1 & 0 & | & 1 & | \\ 2 & 1 & | & -1 & | \end{bmatrix}$ $\rightarrow \begin{bmatrix} 1 & 0 & | & 1 & | \\ 0 & 1 & | & -3 & -1 \end{bmatrix}$

· RepB', B(id) = [-3-1].

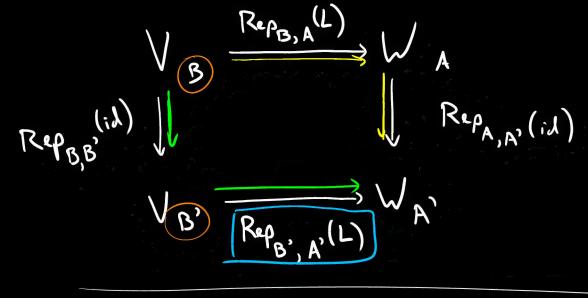
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NB: Rep_{B,B}(id) = In Ly because it times each basis elevat. Comptehnely: [B|B] ~~ [In | In] m Rep_B,B(i). Rep_{B,B},(i) = Rep_{B,B}(i) = In Point: RepB', B(id) = (RepB, B, (id)) VB id VB Prop: An nxn metrix M is a change of basis untrix if and only if M is ususingular. Sketch: If M is nonsingular: then M' exists.

The columns of M' form a basis B for R". Hence we consider the untix representation

Rep_{En,B} (id) = M: $[M^{-1}|I_n] \sim [I_n|M]$ If M is a change of boss where, then $M = \text{Rop}_{B,B}(id)$, so $M^{-1} = \text{Rep}_{B',B}(id)$.

Q: How does changing basis "play with" linear unps in general?
A: Draw a picture.



Pointi We can represent any linear map of finite-dimensional Vector spaces with our preferred bases on the domain and Codomain.

Ex: Consider the linear operator on \mathbb{R}^3 given by $L\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ x + y \end{pmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

Let B = {(-1),(1)} from my makes during lact

Rep_{B,B} (L) = Rep_{B,E3}(i,l) · Rep_{E,E3}(L) · Rep_{E,B}(i,l)

$$\mathbb{R}^{3}_{E_{3}} \xrightarrow{\text{Rep}_{E_{3}}(E_{3},E_{3},L)}
\mathbb{R}^{3}_{E_{3}}$$
Rep_{E3}(i,l) | Rep_{E3}

Hence ne compte RepBB(L) as follows:

$$Rep_{B,D}(L) = Rep_{\Sigma_{3},R}(id) \cdot Rep_{\Sigma_{3},\Sigma_{3}}(l) \cdot Rep_{B,\Sigma_{3}}(id)$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & -1 \\ \frac{1}{2} & \frac{1}{2} & -1 \\ \frac{1}{2} & \frac{1}{2} & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & -2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \qquad Diagond unbix.$$

Point: this map L has a nicer representation with respect to B than E3

The next topic (eigenvalues, eigenvectors, and matrix diagonalization) is absely related to this idea:

Linear operators may have particularly nice representations with respect to some basis other than the standard basis...